



$$1) T_1 = m_1 V_{Bx}^2 / 2 \quad T_2 = m_2 V_{Ay}^2 / 2$$

$$A \xrightarrow{\varphi} B$$

$$V_{Bx} = V_{Ax} - a\varphi' \sin \varphi \Rightarrow V_{Bx} = -a\varphi' \sin \varphi$$

$$V_{By} = V_{Ay} + a\varphi' \cos \varphi \Rightarrow V_{Ay} = -a\varphi' \cos \varphi$$

$$T = T_1 + T_2 = (m_1 a^2 \varphi'^2 \sin^2 \varphi) / 2 + (m_2 a^2 \varphi'^2 \cos^2 \varphi) / 2 = \frac{\varphi'^2}{2} (A \sin^2 \varphi + B \cos^2 \varphi)$$

$$2) K \xrightarrow{\frac{\pi}{2}} O$$

$$V_{Ox} = V_{Kx} - r\omega_z \sin \frac{\pi}{2}$$

$$V_{Kx} = V_{Bx}$$

$$V_{Ox} = V_{Bx} - r\omega_z \sin \frac{\pi}{2}$$

$$3) O \xrightarrow{\frac{\pi}{2}} L$$

$$V_{Lx} = V_{Ox} - r\omega_z \sin \frac{\pi}{2} \Rightarrow V_{Ox} = r\omega_z$$

$$\text{Из 3) и 4) } \Rightarrow r\omega_z = V_{Bx} - r\omega_z \Rightarrow \omega_z = \frac{V_{Bx}}{2r} = \frac{-a\varphi' \sin \varphi}{2r}$$

$$4) Q = \frac{1}{\varphi'} (FV_{Bx} - (m_2 g)V_{Ay} - M\omega_z)$$

$$\frac{\partial}{\partial t} \left( \frac{\partial T}{\partial \varphi'} \right) - \frac{\partial T}{\partial \varphi} = Q$$

$$\frac{\partial T}{\partial \varphi} = \frac{\varphi'^2}{2} (A 2 \sin \varphi \cos \varphi + B 2 \cos(-\sin \varphi)) = \frac{\varphi'^2}{2} (A \sin 2\varphi - B \sin 2\varphi)$$

$$\varphi'' (A \sin^2 \varphi + B \cos^2 \varphi) + \frac{\varphi'^2}{2} (A \sin 2\varphi - B \sin 2\varphi) = Q$$

$$\varphi'' (A \sin^2 \varphi + B \cos^2 \varphi) + \frac{\varphi'^2}{2} (A \sin 2\varphi - B \sin 2\varphi) = \frac{1}{\varphi'} (FV_{Bx} - (m_2 g)V_{Ay} - M\omega_z)$$

